

Toucan Touchscreen Gauge and Trim/Compensation Selection Unit
User Guide V1.86 (Link & Vi-PEC)

Firmware Versions 1.86 and above

Disclaimer

Although every care is taken with the design of this product, JT Innovations Ltd. can in no way be held responsible for any consequential damage resulting from the use of Toucan in your vehicle.

Always operate your vehicle safely and do not allow yourself to be distracted by your Toucan display while driving. Minimise the amount of time you spend viewing the screen. Do not access any function requiring prolonged use of the menus whilst driving.

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Introduction

Thank you for purchasing a Toucan display. We hope it will be easy to install and configure, and we recommend you read this guide before you start. It is recommended that you register your product in the JT Innovations website – this way we can keep you advised of any product updates etc.

Installation

Before You Start

Please check the box contents to ensure nothing is missing. You should have:

toucan Unit



Cable Harness



Mount (one of the following)



Installation

Connectors



6 pin "CAN-F" or PCB connector	Data connection to Link/Vi-PEC ecu
BLACK	Power Ground
YELLOW	Permanent +12V
RED	Switched +12V
ORANGE	Lighting circuit
Multiway	Connects to Toucan unit

ENSURE THE CAR BATTERY IS DISCONNECTED BEFORE ATTEMPTING TO INSTALL YOUR TOUCAN DISPLAY UNIT

IF IN DOUBT, PLEASE CONSULT A QUALIFIED AUTOMOTIVE ELECTRICIAN

Power

The power connectors are provided with "bullet" connectors which may be removed if preferred. Each power feed has an inline fuse holder pre-fitted with a 1 amp 20mm glass fuse. Ensure a good ground connection is provided to the BLACK wire.

To allow Toucan to power up quickly, it is recommended that a connection to both a permanent and switched (i.e. only live when the ignition is on) vehicle battery feed are made. When the ignition is off, Toucan will consume about 40 milliamps from the permanent connection – a typical, healthy, 40 amp-hour vehicle battery will last over a month before being run completely flat by Toucan: but it's your choice.

If you decide not to connect the YELLOW permanent +12 Volt, please make sure it is wired along with the RED connection to the switched ignition feed; otherwise Toucan may not start up when you turn on the ignition.

Toucan will take about 6 seconds to start if the permanent +12 Volt feed is not connected compared to less than a second when the permanent connection is made.

A connection to the vehicle lighting circuit may be made using the ORANGE connector – this will allow the Toucan unit to automatically dim when the vehicle lights are turned on. If not required, please insulate the unused wire to prevent damage to the unit or vehicle.

Multiway Connector

This connects to the rear of the Toucan unit. Note that it has a latching tab that must be depressed before the connector and cable can be detached.

The connector is intended to allow occasional removal of the unit from the car to allow, for example, firmware updates to be applied.



When detaching the unit, take care not to put unnecessary strain on the wires otherwise they may be damaged.

In-vehicle Mounting

Toucan uses the Herbert Richter™ 4-prong mount system, which provides a secure mount when in the vehicle, but easy removal should it be required.

The default mount supplied is a permanent mount which is intended to be permanently screwed to the vehicle. Make sure the mount is in the location you require before attaching it!

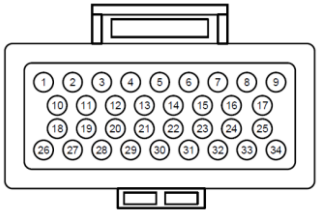
An alternative mount may have been supplied as a choice when you purchased your unit, or they may be purchased separately if required: please contact JT Innovations for availability.

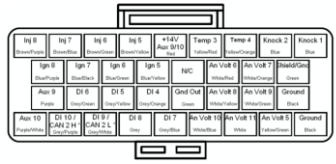
Data Connection 6-pin CAN-F Data Connector

Depending on the ECU variant, the cable you will either use the 6 pin "CANF" connector, or will need a pair of pins to insert into the main ECU header.

NOTE: the CAN connector is NOT the same as that used to map the ECU. It is identical looking, but plugs in to a second header on the ECU board: the necessary cable can be obtained from your mapper/installer, a Link/Vi-PEC dealer or from JT Innovations.

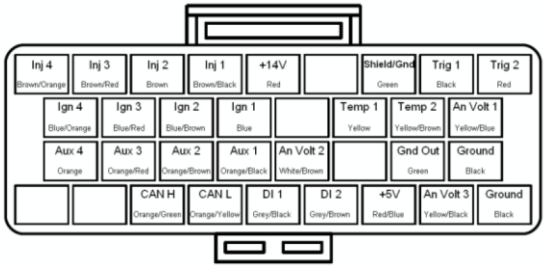
- All G4, G4+ except the Atom, and all V- and i-series ECUs have the 6 pin connector
- G4+ Xtreme and i88 with PCB version 1.4 and newer also have a second CAN interface on the main ECU connector as follows, looking at the rear of the loom plug, as if looking in to the ECU itself:



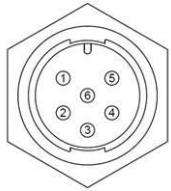


- G4+ Atom only has CANbus on the main ECU connector as follows, looking at the rear of the loom plug, as if looking in to the ECU itself:





- Cut the CAN-F connector off and the SuperSeal pins then need to be inserted in to the correct pin location as above:
  - CAN HI is the BLACK wire of the Toucan cable
  - CAN LO is WHITE wire of the Toucan cable



Looking into ECU connector

The 6 pin CANF connector plugs directly in to the Link/Vi-PEC ecu. For reference:

- Pin 3 is CAN H
- Pin 4 is CAN L.

Link/Vi-PEC Configuration

Having checked the installation of your Toucan, ensuring all connectors are fully home and especially that the power wiring is correct, reconnect the vehicle battery and turn on the ignition. After a few seconds, Toucan should power up and display the main gauge screen. Before it can display any gauges, the ECU must be configured correctly.

Toucan is capable of receiving runtime parameters and status information from Link and Vi-PEC ECUs. Toucan is also capable of activating CAN Digital Input (DI) channels 1 to 8 on Link G4+ and Vi-PEC i-series ECUs.

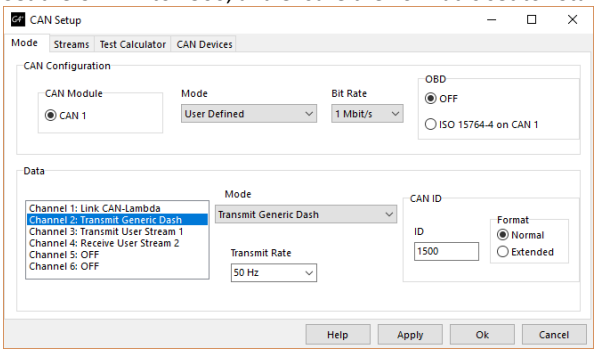
G4 and V-series ECUs with a serial number lower than 10,000 will need a CAN upgrade performed before they can communicate with CAN devices. Consult your dealer.

To control DI channels you will need to download “Toucan CAN Extra Frame V180 onward.lcs” and “Toucan CAN DI V186 onward.lcs” from the JTi website (www.jti.uk.com/downloads). Place these file in the Link PCLink G4+ installation folder named “CAN” – this is usually located at “C:\Link G4\PCLink G4+\CAN”.

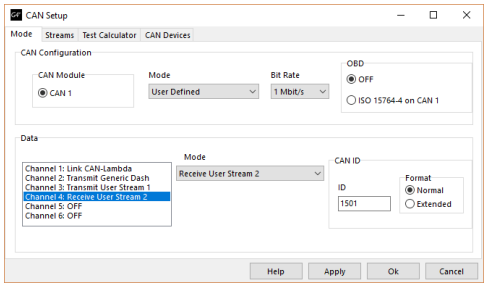
You must also use PCLink or iVTS version 5.1.0 or newer. If necessary download the latest version from the Link/Vi-PEC website.

Configured your system as follows using PClink or iVTS as appropriate:

1. Open the CAN Setup window: ECU Controls | CAN Setup
2. Select the CAN module to be used
3. Set the Mode to 'User Defined'.
4. Configure the Bit Rate to 1 Mbit/s
5. Select a spare CAN channel.
6. Select 'Transmit Generic Dash' from the Mode drop-down menu.
7. Set the Transmit Rate to 20 Hz.
8. Set the CAN ID to 1500, and ensure the Format is set to “Standard”



9. Select the next spare CAN Channel.
10. Select ‘Transmit User Stream **X**’ from the Mode drop-down menu (where ‘**X’** is the next unused transmit or receive user stream number.
11. Set the CAN ID also to 1500, transmit rate to 20Hz, and ensure the format is set to “Standard”.
12. Select 'Receive User Stream **Y'** from the Mode drop-down menu (Where ‘Y’ is the next unused transmit or receive user stream number).
13. Set the CAN ID to 1501.
14. Ensure the Format is set to “Standard



15. Change to the Streams tab of the CAN Setup window. Select Stream **X** – where “**X”** is the stream selected above - and then click Load Stream.
16. Select ‘Toucan CAN Extra Frame V180 onward.lcs’ and click the Open button.
17. Select Stream **Y** (where “**Y”** is as selected above) and then click Load Stream.
18. Select ‘Toucan CAN DI V180 onward.lcs’ and click the Open button.
19. Make sure no other CAN channels are configured on the same CAN IDs.
20. Click Apply and then OK.
21. Make sure a Store (F4) is performed.

Link G4/G4+ Mode

Use “More” menu 4 to choose between G4 and G4+ modes – this is important to correctly display lambda values received as they differ between the models. Also note that the G4 does *not* support DI control. Use G4+ for Vi-PEC i-series models and G4 for Vi-PEC V-series models.

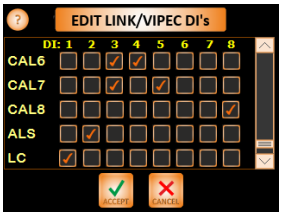
Link/Vi-PEC DI Control Functions

Link G4+ and Vi-PEC i-series ECUs allow a wide range of parameters to be controlled via a CANbus message that acts as a “Digital Input”. This includes functions such as launch control on/off, anti-lag on/off, fuel table switching, boost limit switching, etc.

Toucan has dedicated touch controls for launch control and antilag activation. In addition it provides 8 “Calibration” (“CAL”) selections that can be used to control any combination of the 8 DI channels available from Toucan.

To make use of these functions, User Inputs must be configured using the Link/Vi-PEC Ecu Manager software to correctly assign functions to the relevant DI channel(s).

Toucan Configuration



This is accessed via the "More" menus on page 4.

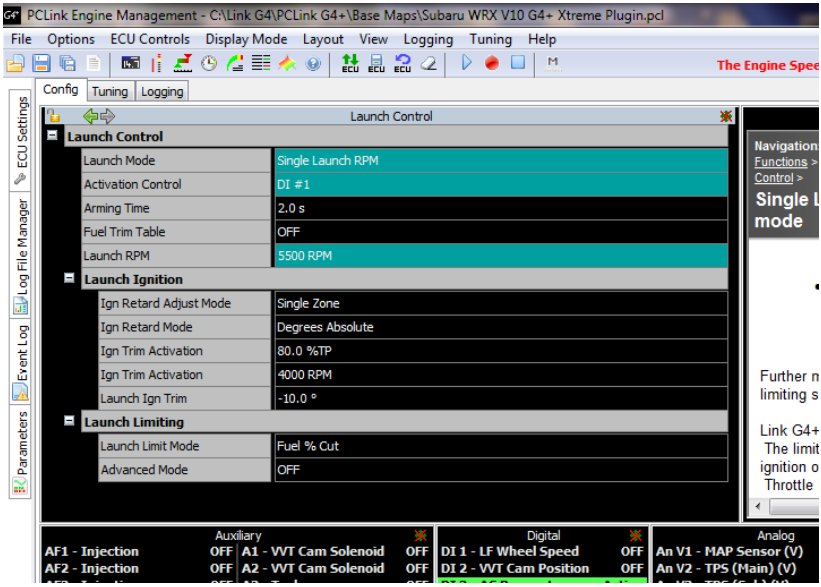
A grid of all 8 available DI channels against the 8 "CALs", plus the launch and antilag button functions is presented. You now select the required DI's to be transmitted for each of these functions. CALs have User text that may be used to describe the function of each Cal (see later).

ECU Configuration - Launch Control

You may wish to consult with your mapper before configuring Launch Control.

To allow Toucan to turn launch control on or off:

- Go to "ECU Settings | MotorSport | Launch Control
- Set the Launch Mode to any mode but "OFF"
- Set Activation Control to the required DI (e.g. CAN DI #1 – Note: *not* "DI #1"; it must be "CAN DI #1")

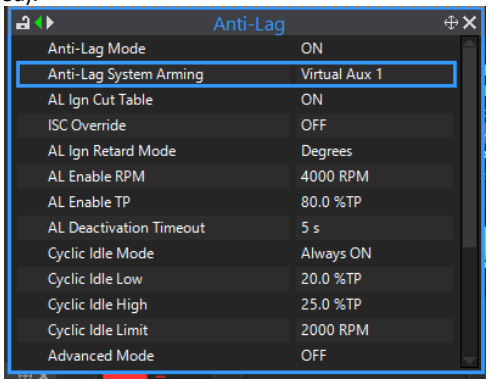


ECU Configuration – ALS on/off

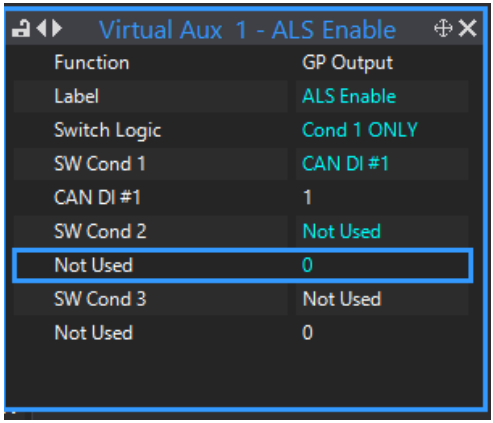
You may wish to consult with your mapper before configuring AntiLag.

To allow Toucan to turn ALS on or off:

- Go to “ECU Settings | MotorSport | Anti-Lag”
- Set the Launch Mode to “ON”
- Set the Anti-Lag System Arming to “Virtual Aux 1” (Virtual Aux 2 or 3 can be used instead if preferred).



- Go to “ECU Settings | Auxiliary Outputs | Virtual Aux 1”
- Set the Mode to “GP Output”, Switch Logic to “Cond 1 Only”. Give it title, such as “ALS Enable”
- Set Sw Cond 1 to required CAN DI (e.g. CAN DI #1 – Note: *not* “DI #1”; it must be “CAN DI #1”)
- Set the parameter now labelled with the CAN DI chosen to be “=1”.



ECU Configuration –CAN DI functions for CALs

You may wish to consult with your mapper before configuring other functions to CAN DIs (Note: *not* “DIs”; it must be “CAN DI”s).

First, consider what functions you wish to have on each of the 8 CALs. Typical usage might be low and high boost settings, and fuel/ignition tables for different fuel types. As an example, this could be set as follows:

- Go to “ECU Settings | Boost Control | Multiple Boost Tables
- Set the Active tables to “2 tables” or “3 tables” as required
- Set Activation Control to the required CAN DI (e.g. CAN DI 3 and 4)
- Go to “ECU Settings | Fuel | Fuel Corrections | Dual Fuel Table
- Set any mode other than “OFF”
- Set Activation Control to the required CAN DI (e.g. CAN DI 5)
- Go to “ECU Settings | Ignition | Ignition Corrections | Dual Ign Table
- Set any mode other than “OFF”
- Set Activation Control to the required CAN DI (e.g. CAN DI 7)

For the purposes of illustration, let’s assume:

- Boost table 1 is low boost (default)
- Boost table 2 is high boost (activated by CAN DI3)
- Pump fuel is fuel table 1 (default)
- Race fuel is fuel table 2 (activated by CAN DI5) and this needs ignition table 2 on CAN DI7

In reality other tables, such may need to be configured too. However, as an example, Toucan could now be set up as follows:

- CAL1: no CAN DIs controlled - low boost, ignition table 1 and pump fuel.
- CAL2: trigger CAN DI3. This would be high boost and pump fuel
- CAL3: trigger CAN DI5 and 7. This would be low boost and race fuel
- CAL4: trigger CAN DI3, 5 and 7. This would be high boost and race fuel.

ECU Configuration –Anti-Theft

Toucan allows “CAL 9” to be used to enable an immobiliser/anti-theft function. In combination with requiring a PIN to change to or from the last CAL (CAL 9 in this case) this can be a useful additional level of security.

To enable this function, you must have configured the “Toucan CAN DI V180 onward.lcs” datastream as described earlier :

- Go to “ECU Settings | Chassis and Body | Anti Theft”
- Set “Allow CAN Anti-Theft Request” to “Yes”
- Set the “CAN Anti-Theft Default State” to “Immobilised”

Menus and Operation

Gauge Screens

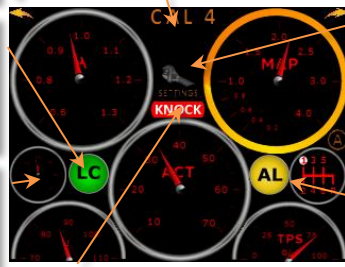
Touch here to change current calibration. Label shown is the first 5 characters of the text entered.

Touch here to go to previous gauge page

Touch here to go to next gauge page

Touch here to enter SETTINGS menus

Touch to turn launch control on or off
- Red - off
- Green – on



Shows which gauge screen is showing: A, B, C or D.

Touch the centre of any gauge to display the full screen version and then cycle through all gauges or reset the peak marker.

Press and hold any gauge to display the most recently shown large gauge.

Return to the main gauge screen by touching the centre of the large gauge.

Knock warning. Also shows sensor alarms or Check Engine light using different icons. Touch the icon to bring up a display of current sensor

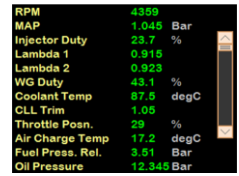
Touch to cycle through both available antilag maps.
- Red – off
- Yellow – ALS1
- Green – ALS2

Four gauge screens are available with complete flexibility of which gauge is displayed where. This can be configured via the Gauge Select pages, accessible via the “Gauge Setup” button.

Only data from sensors that are actually connected to the ecu and are configured correctly can actually be displayed.

Large Gauges

Goes to parameter list view.



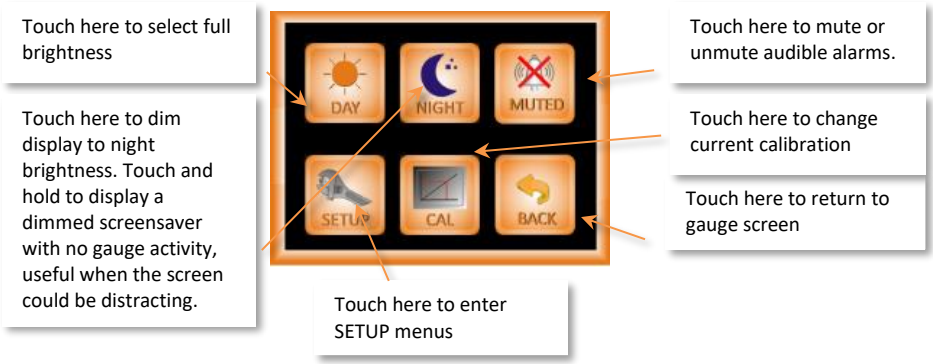
Touch here to return to main gauge screen.



Touch here to mute an active alarm. Will be automatically unmuted when this alarm clears

Resets the peak marker.

Settings Menu



If the "illumination" wire has been wired to the vehicle's lighting circuit, the manual day and night buttons will temporarily override the brightness as controlled from the vehicle lighting stalk.

Setup Menu

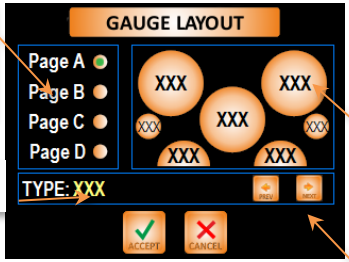


Gauge Layout

This is accessed via the Gauge Setup button, and then “Gauge Select”.



Touch here to select which of the 4 pages to setup



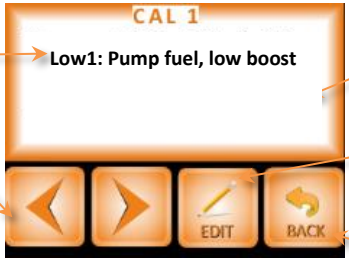
Touch the gauge that you wish to change. A 3 letter mnemonic describes the current gauge selected for each position

Gauge name is shown

Touch here cycle between the next and previous gauges in the list

CAL Selection Menu

First 5 characters of this text used on main gauge screen as label.



User Text describing this calibration function

Next and previous buttons to select a different setting

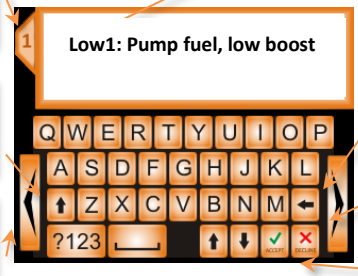
Touch here to edit the User Text

Touch here to return to previous menu

Editing CAL Text

First 5 characters used as label on main screen

The text being edited.



Backspace (delete character to left)

Shift key to access lower case characters, symbols, etc.

Move the cursor up or down the 3 lines of text

Next and previous buttons to select a different CAL

Touch here to return accept or

CAL PIN Protection.

If enabled via the “more” menus, Toucan can be set to prevent the current CAL being changed unless you enter a 4-digit PIN. This can be useful if you have a “valet” mode (with reduced rpm limit for example) and/or an anti-theft CAL. You can also set PIN protection to *only* apply to the last CAL (i.e. CAL 8), *only* to the first CAL or to *both* the first and last CAL.

There are a few things to be aware of if you choose to use this option:

- The default PIN is 0000 and it is recommended that you change this to something else.
- Once PIN protection is enabled, the (correct) PIN will need to be entered before you can change the PIN, or to disable PIN protection again.
- If the PIN is entered incorrectly 3 times, PIN entry will be prevented for the next 10 minutes. Note that this 10-minute timeout will be reset if power is removed from the unit.
- In the event that Toucan is disconnected from the Syvecs ecu, the ecu will, in most cases default to CAL 8 (although this can be CAL 1 if a Syvecs input with no pull-up resistor is used). It is generally recommended that the valet or anti-theft CAL is in position 8, or the PIN protect first CAL function (or first *and* last) is used.
- In the event that you forget the PIN it can be reset using a PC programme, connecting to Toucan via USB. This programme is available from the JT Innovations website, or contact technical support for assistance.



Alarm Configuration

The Alarms configuration menu allows you to determine which parameters will cause alarm events. A setting allows the audible alarm to be muted if the engine is not running.

An alarm event will:

- Cause an audible warning, unless Toucan is muted
- Cause the bezel of the relevant gauge to change to a flashing orange
- If enabled, cause the relevant gauge to be displayed full screen.

In addition, there is a low oil temperature warning that can be enabled. This will not sound the audible alarm, but will display a non-flashing orange bezel until the oil temperature exceeds the configured temperature. Obviously this function only works if an oil temperature sensor is connected to your ECU.

When an alarm is activated, the relevant large gauge has a mute button. This may be used to temporarily mute that specific alarm. It will remain muted until either that alarm condition clears or Toucan is repowered. Alarms for other fault conditions will not be supressed or muted.

Available Alarms

- ACT. Any value in range, in 1°C steps. Alarm triggered if alarm value is exceeded. Default 50C.
- Battery voltage. Any value in range in 0.25V steps. Alarm triggered if current value is below alarm threshold. Default 11.5V
- Boost. Any value from 0 to max, in 0.05 bar increments. Alarm triggered if alarm value is exceeded. Default 1.5bar.
- Coolant temperature. Any value in range in 1°C steps. Alarm triggered if alarm value is exceeded. Default 95C.
- Exhaust Temperature (EGT1 and EGT2). Any value in range in 10°C steps. Alarm triggered if current value is above alarm threshold. Default 850C.
- Fuel Level Low. 0-100% in 1% increments. Alarm is triggered if current level is below the alarm value, default 10%.
- Fuel Pressure. Any value in range in 0.1bar steps. Alarm triggered if current value is below alarm threshold. Default 2 bar.
- Fuel Temperature. Any value in range in 1°C steps. Alarm triggered if current value is above alarm threshold. Default 70C.
- Injector Duty Cycle. Any value up to 100% in 1% steps, default 85%. Alarm triggered if injector duty cycle exceeds the alarm threshold.
- Knock detected.
- Lambda 1 and Lambda 2. Any value in range, in 0.01 steps. Alarm triggered if alarm value is exceeded. Default 1.05.
- "Lean Lambda". Alarm is triggered if lambda exceeds set value AND RPM is above set value AND Boost exceeds set value.
- Boost. Any value in 0.05 bar increments. Alarm is triggered if alarm value is exceeded. Default 2.5bar
- Oil Pressure. Any value in range in 0.1bar steps. Alarm triggered if current value is below alarm threshold. Default 2 bar.
- Oil Temperature. Any value in range in 1°C steps. Alarm triggered if alarm value is exceeded. Default 120C.
- Oil Temperature Low. Any value in range in 1°C steps. Alarm triggered if current value is below alarm threshold. Default 70C.
- RPM. Any value in range 0-10,000 rpm in 100rpm steps. Alarm triggered if alarm value is exceeded. Default 7500.
- Sensor Alarms. Any sensor in a fault state will cause an alarm.
- TPS. Any value 0-100%, 5% steps. Alarm triggered if alarm value is exceeded. Default 50%.
- Wheel speed. Any value in range in 1mph or 1kph steps. Alarm triggered if alarm value is exceeded. Default 70mph/120km/h

"More" Menus

The more menus allow you to select

- Units used – Metric, Imperial or "USA" (which uses Imperial measurements for everything except Boost and MAP which are in kPa)
- Speed display – mph or kph
- Gear display – H pattern or digits
- Whether the large full screen gauge should be automatically displayed should the gauge start showing an alarm
- Whether changing the CAL should be PIN protected – either all of them, or just the last CAL.
- Change the CAL PIN
- Select Absolute or Relative Fuel Pressure (Relative only available if CAN bus or custom serial data selected).
- Enable/Disable the display of peak markers on gauges. Peaks are remembered until manually reset on the large gauge display.
- Enable/disable dynamic peak markers. Dynamic peak markers maintain the current peak for just a few seconds and then drop back to the current reading. The hold period can be adjusted.
- Choose the ECU interface (STACK, CAN or Syvecs customer serial data)
- Choose the CAN data rate (1Mbit or 500kbit)
- Edit Digital Inputs (DIs) sent for CALs 1 to 8, launch control, and antilag control
- Choose between Link G4 and G4+ models.
- Mute alarms if the engine is not running - useful if the vehicle is not being driven, but the ignition is switched on.
- Turn the audible touchscreen feedback beep on/off
- Determine which large gauges will be displayed when you cycle through them. This is useful to hide gauges when the appropriate gauge sensor hasn't been fitted.
- Display CAN termination on/off, software version and current/actual CAL voltage

CANbus Termination

It may be necessary to enable the bus termination if Toucan is the last device on the CANbus network. By default the termination is switched off, but it may be enabled by sliding the small switch on the rear of the unit towards the 4-prong mounting plate. You may need to use a small screwdriver to access the switch through the rear cover.

You can confirm the status of the termination switch via the "more" menus.

Other Functionality

Sensor Errors and Limit Flags

The ECU datastream includes a number of error, status and limit flags that can be decoded and displayed on Toucan.

If the sensor alarm is enabled, any such status message will cause a small “sensor alarm” icon to be displayed in the main gauge screen. If the sensor alarm large gauge is enabled, a large alarm indicator will be shown, and this then shows the error number and the decoded message.

You may need to refer to Link/Vi-PEC documentation for a detailed explanation of any error message.

Knock Level and Injector Duty – Realtime Display

If enabled as large gauges, the full screen knock level and injector duty “gauges” will show a realtime display of the knock level and injector duty.

Status Indicators

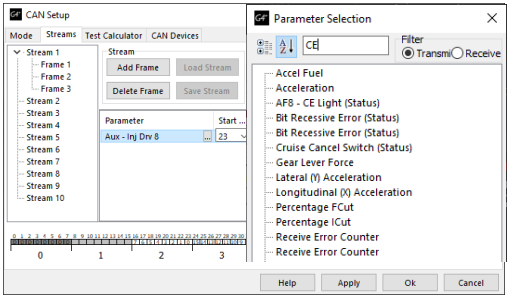
There are two status indicators that can be added to the main gauge pages, via the gauge setup menus. Status 1 shows “RPM Limit” and Status 2 shows Traction Control status.

For these to be displayed: go to Settings | Setup | Gauge Setup. From there you may change either or both of the tiniest gauges to be “Status 1” or “Status 2” – these are RPM and MAP respectively. This can be done on any or all gauge pages, as wished.

Check Engine Light

The G4+ is inconsistent with the way the Check Engine (CE) light is managed. Although the parameter is defined in the stream applied (see earlier) it will need to be reconfigured on a per-vehicle basis.

Using PC Link navigate to the CANbus “streams” tab for the .lcs file loaded as a stream for the extra frames, and locate frame 3. And click on the Parameter “Aux – Inj Drv 8”. This will cause a button with 3 dots to appear. Click on the dots and type “CE” in the parameter selection search box. Locate the parameter labelled “CE Light” and click “OK”, then “apply” and “OK” to save the new CAN setup, and store to the ECU.



Firmware Updates

Occasional firmware updates will be made available to add new features. These may be downloaded from the Downloads section of the JT Innovations website.

Updates are applied using a PC program (also available from the website) and a standard "mini" USB cable. Updates should be applied with the Toucan disconnected from the vehicle. It will be powered from the PC USB port, although the LCD will be shut down.

Technical

Data Interface	CAN 2.0B at 1Mbit/s or 500kbit/s with selectable termination, or RS232 at 9600 baud or 115.2kbaud
Expansion Connector	RS232, CAN, Power Out and Ground. Allows connection of toucan expansion accessories, available in 2012.
Power	8-20V <200mA typ. <40mA in standby mode Connections to permanent, switched and illumination power, via 1A fused connections.
Memory	Non-volatile storage of all parameters
Firmware Updates	Via rear-panel USB connector, using PC programme.
Compliance	Directives: 2002/96/EC, 72/245/EC, EN50498:2010
Warranty	1 year
Dimensions	100x83x16mm
Weight	200g
Display	3.5" QVGA TFT, 320x240 pixels, 24 bit colour, with touchscreen
Processing system.	190MHz 32 bit ARM9, 8Mbytes Flash memory, 8Mbytes SDRAM.
Package contents	Toucan unit, power/data cable harness, mount, installation guide.
Available Gauges/Alarms	Air intake temperature; Battery Volts; Boost (2.5 bar and 3.5 bar); Exhaust Gas Temperature (2 channels); Fuel level; Fuel Pressure; Fuel Temperature; Current Gear; Injector Duty warning; Knock; Lambda (2xwideband channels, 1x narrowband); Lean Lambda warning; Engine limp/Cut mode; MAP; Oil Pressure; Oil Temperature; RPM; Sensor Error; Throttle Position; Coolant Temperature; Wheel Speed.

Glossary

Term	Description
ACT	Air Charge Temperature
CANbus	"Controller Area Network" bus – a serial interconnect common in vehicles.
ECT	Engine Coolant Temperature
EGT	Exhaust Gas Temperature
EOP	Engine Oil Pressure
EOT	Engine Oil Temperature
FP	Fuel Pressure
MAP	Manifold Absolute Pressure
TPS	Throttle Position Sensor

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